# Obin Kwon

Contact Information	<pre>PhD Candidate in Robot Learning Laboratory, Seoul National University Seoul, South Korea E-mail: obin.kwon@rllab.snu.ac.kr Linkedin: https://www.linkedin.com/in/obin-kwon-as Homepage: https://obin-hero.github.io Mobile: +82 10-7651-4307</pre>	99a37193/	
Research Interests	<ul> <li>Vision-based Robot Control, Embodied AI, Robot Learning</li> <li>Scene Representation, Localization and Mapping</li> <li>Decision Making, Imitation Learning, Reinforcement learning</li> </ul>		
Skills	<b>Programming Language:</b> Python, C++, MATLAB <b>Software:</b> ROS, PyTorch, TensorFlow, OpenCV		
Experience	<ul><li>Sequor Robotics, AI/Robotics Researcher.</li><li>Seoul, Korea</li><li>Developing a visual localization system in warehouses.</li></ul>	Oct. 2023 - Now	
	<ul> <li>NAVER LABS, Research Intern.</li> <li>Seongnam, Korea</li> <li>Developed a visual localization system based on simple was</li> </ul>	Jan. 2023 - July. 2023 ayfinding maps.	
Education	<ul> <li>Ph.D. in Electrical and Computer Engineering</li> <li>Seoul National University, Seoul, Korea</li> <li>Integrated Msc./Ph.D course</li> <li>Advisor: Prof. Songhwai Oh (songhwai@snu.ac.kr)</li> </ul>	2018 - 2024 (Expected)	
	<b>B.S. in Electrical and Computer Engineering</b> - Seoul National University, Seoul, Korea	2014 - 2018	
Publications	<ul> <li>Obin Kwon, Dongki Jung, Youngji Kim, Soohyun Ryu, Suyong Yeon, Songhwai Oh, Donghwan Lee, "WayIL: Image-based Indoor Localization with Wayfinding Maps", <i>IEEE International Conference on Robotics and Automation (ICRA)</i>, 2024. (accepted)</li> <li>Jeongho Park, Obin Kwon and Songhwai Oh "Attention-Based Randomized Ensemble Multi-Agent Q-Learning," <i>IEEE International Conference on Control, Automation and Systems (ICCAS)</i>, Oct. 2023.</li> <li>Obin Kwon, Jeongho Park, and Songhwai Oh, "Renderable Neural Radiance Map for Visual Navigation," <i>IEEE Conference on Computer Vision and Pattern Recognition (CVPR)</i>, Jun. 2023. (Highlight, Acceptance Rate: 2.5%)</li> </ul>		
	Nuri Kim, <b>Obin Kwon</b> , Hwiyeon Yoo, Yunho Choi, Jeongho Park, and Songhwai Oh, "Topological Semantic Graph Memory for Image-Goal Navigation", <i>Conference on Robot Learning (CoRL)</i> , Dec. 2022. (Oral, Acceptance Rate: 6.5%)		

	Hyemin Ahn <sup>*</sup> , <b>Obin Kwon</b> <sup>*</sup> , Kyungdo Kim, Jaeyeon Jeong, Howoong Jun, Hongjung Lee, Dongheui Lee, and Songhwai Oh, "Visually Grounding Language Instruction for History-Dependent Manipulation", <i>IEEE International Conference on Robotics and Automation (ICRA)</i> , May. 2022. (* equal contribution)		
	<b>Obin Kwon</b> , Nuri Kim, Yunho Choi, Hwiyeon Yoo, Jeongho Park, and Songhwai Oh, "Visual Graph Memory with Unsupervised Representation for Visual Navigation", <i>IEEE/CVF International Conference on Computer Vision(ICCV)</i> , Oct. 2021.		
	<b>Obin Kwon</b> and Songhwai Oh, "Image-Goal Navigation Algorithm using Viewpoint Estimation," <i>IEEE International Conference on Control, Automation and Systems (ICCAS)</i> , Oct. 2021.		
	Minyoung Hwang, <b>Obin Kwon</b> , and Songhwai Oh, "Geometric Understanding of Reward Function in Multi-Agent Visual Exploration," <i>IEEE International Conference on Control, Automation and Systems (ICCAS)</i> , Oct. 2021.		
	<b>Obin Kwon</b> and Songhwai Oh, "Learning to Use Topological Memory for Visual Navigation", <i>IEEE International Conference on Control, Automation and Systems (ICCAS)</i> , Oct. 2020.		
Honors	Scholarships		
	Lecture & Research Scholarship - Seoul National University	Spring 2024	
	Brain Korea 21 Plus Scholarship Fall 2020-Spring 2 - Seoul National University	Fall 2020-Spring 2022, Fall 2023 Spring 2015 - Fall 2017. ter Scholarship Foundation	
	Kim Jeong-sik Special ScholarshipSpring 20- Kwanak Corporation, SNU Electrical and Compucter Scholarship Foundati- Full tuition + $\alpha$		
	Merit-based University Admission Scholarship - Yongin City Scholarship Foundation	Spring 2014	
Research Experiences	Robot Learning: Efficient, Safe, and Socially-Acceptable Machine Learning, - Funded by Ministry of Science and ICT (MSIT)	2019 - Now	
	AI Technology for Guidance of Mobile Robots with Uncertain Maps, - Funded by Ministry of Science and ICT (MSIT)	2019 - 2023	
	Autonomous Navigation Multi-Agent Deep Reinforcement Learning, - Funded by Hyundai Autoever	2020 - 2021	
Teaching Experiences	<ul> <li>Teaching Assistant @ Seoul National University</li> <li>Deep Reinforcement Learning (Topics in Control and Automation)</li> <li>Theory and Lab of IoT, AI, and Big Data</li> <li>Introduction to Intelligent Systems</li> </ul>	Spring 2021 Fall 2019 Fall 2018	
Professional Services	<ul> <li>Reviewer</li> <li>Robotics Science and Systems.</li> <li>Robotics &amp; Automation Letters.</li> <li>Transactions on Robotics.</li> </ul>		

- Transactions on Pattern Analysis and Machine Intelligence.
- Transactions on Automation Science and Engineering.
- International Conference on Intelligent Robots and Systems.
- Ubiquitous Robots.

#### Talk

- Invited tech talk at NAVER, Feb, 2022.

#### References Prof. Songhwai Oh

- Professor at Department of Electrical and Computer Engineering, Seoul National University.

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## Prof. Hymin Ahn

- Assistant Professor at Artificial Intelligence Graduate School (AIGS), Ulsan National Institute of Science and Technology(UNIST)

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### Prof. Sungjoon Choi

- Assistant Professor at Department of Artificial Intelligence, Korea University

- Email: sungjoon-choi@korea.ac.kr